## Todays Agenda

- -> kecap the CS algo /
- -> Reprove the hoiseless setting
- -> show that goversion matrices satisfy good RIPO

D We pick a sensing matrix φ ∈ IR™xn

② Adversary picks x, ||x||<sub>0</sub> = k, x ∈ IR<sup>n</sup>

(3) We observe  $\phi x = y \in \mathbb{R}^m$ (4) Can we recove x from y?

Try to make of as small as possible

## Algo [ candy - Tao]

Algo [ Canded - 120]

Choose 
$$\varphi$$
 to be  $(\delta, k) - RIP$  matrix

$$= \sum_{k=1}^{\infty} |A|^2 \leq |A|^2 \leq$$

$$\frac{\left(\left\|\frac{1}{2}\right\|_{2}^{2}}{\left(-\delta\right)} \leq \left\|\left(\frac{1}{2}\right)\right\|_{2}^{2} \leq \left(1+\delta\right)$$

y = px is observed

Output 1.

Mot : Counder error vector

h = x" - x We'(1 show |1hl/2 = 0 4(2k, 8) < \frac{1}{3}, then x\* = x

break up co-ordinates into disjoint sets To, Ti, To,

. L. ANIM YL

To = K- non-zero coordinates in unknown, So, h = \( \sum\_{130} \lambda\_{1j} \) Part 1 bound 11h Toutzo 112 Part @ bound 11 hour, 112 11 h 72 112 5 JK 11 h 72 110 < \frac{1}{\int\_K} || h\_{\overline{1}||\_2} (max coordinate in \overline{1}\_2) 11 h T3(12 & 1 h T2 11 2 [[ A<sub>toυ7, y</sub>dl<sub>2</sub> ≤ ∑ || h<sub>Tj</sub>||<sub>2</sub> ≤ ∫<sub>k</sub> || h<sub>Tj</sub><sub>1</sub><sub>1</sub><sub>2</sub>∪... ||<sub>1</sub> = ∫<sub>k</sub> || h<sub>To</sub>||<sub>1</sub> (Now, 1) | L<sub>1</sub>, + C<sub>13</sub>+... - 11<sub>2</sub> We ophonized the 11x\*14 . Opt som to it wised the  $\|x^*\|_{\underline{1}}$  or  $\|x^*\|_{\underline{1}}$   $\|x^*\|_{\underline{1}}$   $\|x^*\|_{\underline{1}}$   $\|x^*\|_{\underline{1}}$   $\|x^*\|_{\underline{1}}$   $\|x^*\|_{\underline{1}}$ => (| x - bll, < |1x112  $\|(x-h)_{70}\|_{1} + \|(x-h)_{70}\|_{2} \leq \|x_{70}\|_{2}$   $\|x_{70}\|_{1} - \|h_{70}\|_{1} + \|h_{70}\|_{1} \leq \|x_{70}\|_{2}$ (F) => || h(ToUT) || 2 < JR || h To || 1

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=> (1-5) | hrought < 25 | hrought \( \frac{5}{122} \) < 28 11 hour, 1/2 · Jk 11 hours (A&B) (5 28 1 , JK | | h 70 | 12

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$$\Rightarrow (1-5) || h_{T_0 \cup T_1}||_2 \leq 25 || h_{T_0 \cup T_1}||_2$$

$$\Rightarrow (1-35) || h_{T_0 \cup T_1}||_1 \leq 0$$

$$\Rightarrow || h_{T_0 \cup T_1}||_1 = 0 (5 < \frac{1}{3})$$

$$\Rightarrow h = 0 || h_{T_0 \cup T_1}||_1 = 0 (5 < \frac{1}{3})$$

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$$\Rightarrow h = 0 || h_{T_0$$

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 $m = \Theta(k \log \frac{n}{k})$ So, we're good

if -E'm o(k) < 1/2 Overall failure probability We're Shown (except for union bound) that m= O(Klorn) suffices! How to union bound one infinitely many vectors ?? Fix la coordinates as  $\{1, 2, ... k\} \leftarrow WLOGI.$ there are so wasy unit rectors 11×11=)  $X = \left\{ x : \frac{1}{2}x_{1}^{2} = 1 \right\}$  are unit vectors! Find a just N ("net") ist + x E X, 112-11/2 < 8 balls of radius & around net points should coree X How swall can N be? Start with orbitary do, add JbN
As long as JXEX A d(x, N) > E,
add 2 to N. → greedy € - wt. H n₁, n₂ ∈ N, we have  $|| \mathbf{T}_1 - \mathbf{n}_2 ||_2 > \epsilon$ ⇒ B(n; =) ~ B(n; =) = Þ

